

Introduction

- Precise Evapotranspiration (ET) estimation supports effective water resource management.
- The PT–JPL model estimates ET by incorporating biophysical constraints into the Priestley–Taylor equation.
- In contrast, the Penman–Monteith (PM) model integrates aerodynamic and surface resistance parameters.
- These fundamental differences in formulation and parameterization can lead to varying model performance across different environmental conditions.

Objective:

• This study evaluates the performance of the PT–JPL and PM models over five flux tower sites in Arizona by comparing model outputs with observed data using statistical metrics and distribution analyses.

Study Area:

 Arizona's climate characterized by arid to semiarid conditions, with high temperatures, limited annual precipitation, and strong seasonal variability



Fig. 1. Study area and site locations

Datasets:

Dataset Type				
Air Temperature	PM and PT-JPL			
Air Pressure	PM and PT-JPL		AORC Version 1.1	
Wind Speed	PM			
Specific Humidity	PM and PT-JPL	AORC		
Downward Shortwave/Longwave	PM and PT-JPL			
Precipitation	PM			
LAI	PM		MOD15A2H level 4	
Emissivity	PM and PT-JPL		MOD21A2 Version 6	
Land Cover	PM	MODIS	MCD12Q1 Version 6 (LC_Type1)	
Albedo	PM and PT-JPL	ERA5 Land	ERA5 Land	
NDVI	PT-JPL	MODIS	MOD13Q1	
Observed ET	PM and PT-JPL	AmeriFlux	AmeriFlux	

Table 1. Dataset used in this study to develop and validate both models

ET Modeling:

- ET was estimated using two approaches: the PT-JPL model and PM model.
- Both model outputs were compared to observed ET using metrics including Kling–Gupta Efficiency Skill Error (KGEss), coefficient of determination (R²), and Root Mean Square Error (RMSE).

Kolmogorov–Smirnov (K–S) Test:

• This non-parametric test quantifies the maximum absolute difference (D) between the empirical cumulative distribution functions (CDFs) of the observed ET and the ET estimates from each model.

Abdul Wahed Nab¹, Muhammad Jawad¹, Ali Behrangi¹, Guo-Yue Niu¹ ¹Department of Hydrology and Atmospheric Sciences, The University of Arizona, Tucson, AZ



Table 2. Comparison of PT-JPL and PM model performance against observed latent heat flux across multiple flux tower sites.



3 -	- 2022	2022 – 2024					
	RMSE	Bias Ratio	KGEss	R ²	RMSE	Bias Ratio	
7	21.36	0.6	0.80	0.68	19.25	0.5	
7	16.04	0.5	0.86	0.73	14.87	0.5	
9	25.97	1.2	0.53	0.69	23.97	1.0	
3	20.71	0.8	0.81	0.75	18.11	0.6	
3	23.96	0.9	0.66	0.61	21.06	0.8	
4	21.61	0.8	0.73	0.69	19.45	0.69	
9	19.76	0.5	0.80	0.75	18.34	0.5	
5	15.02	0.5	0.88	0.83	11.66	0.4	
3	13.12	0.6	0.86	0.68	16.52	0.7	
7	14.91	0.6	0.85	0.78	15.60	0.5	
1	26.24	1.0	0.80	0.65	16.30	0.6	
1	17.81	0.64	0.84	0.74	15.68	0.54	





- W/m^2) for both periods.

- at higher fluxes.
- predictive accuracy.

This study was supported by the Arizona Tri-University Recharge and Water Reliability Project, and NOAA, awarded to the Cooperative Institute for Research on Hydrology (CIROH) through the NOAA Cooperative Agreement with The University of Alabama, NA22NWS4320003.



3. Results

4. Conclusion

 PM outperforms PT–JPL, with higher average KGEss (0.72–0.84), R² (0.61–0.74), and lower RMSE (15.68–17.81 W/m²) compared to PT–JPL (KGEss: 0.68–0.73, R²: 0.54–0.69, RMSE: 19.45–21.61

• The bias ratio analysis further supports this, showing lower average bias ratios for PM (0.64–0.54) than PT–JPL (0.80–0.69).

• The K–S test confirms significant differences (p < 0.001) between observed and modeled ET distributions, with D = 0.09-0.32 for PT-JPL vs. observed and D = 0.06-0.19 for PM vs. observed.

• PT–JPL overestimates ET, while PM underestimates it, particularly

• This discrepancy underscores the need for further refinement in model parameterization, improved input data resolution, and incorporation of additional environmental constraints to enhance

• Future research should integrate machine learning techniques, data assimilation methods, and enhanced meteorological datasets to optimize ET model performance in water-limited environments.

Acknowledgments